

An Optimization Algorithm for the Tourist Trip Design Problem with Type-Covering Constraints

Xabier A. Martin, Javier Panadero, Angel A. Juan xamarsol@upv.es

Dept. of Applied Statistics and Operational Research, and Quality Universitat Politècnica de València, Campus de Alcoy, Spain







Contents

- I. Introduction
- **II.** Problem Description
- **III. Preliminary Results**
- IV. Conclusions and Future Research

Part I: Introduction



 The challenge is how to decide which places to visit.



- The challenge is how to decide which places to visit.
- This is the core concept of the TTDP.





 The TTDP allows tourist route planning based on preferences.



- The TTDP allows tourist route planning based on preferences.
- Objective is maximize profit or preference value of visited POIs before maximum travel time.





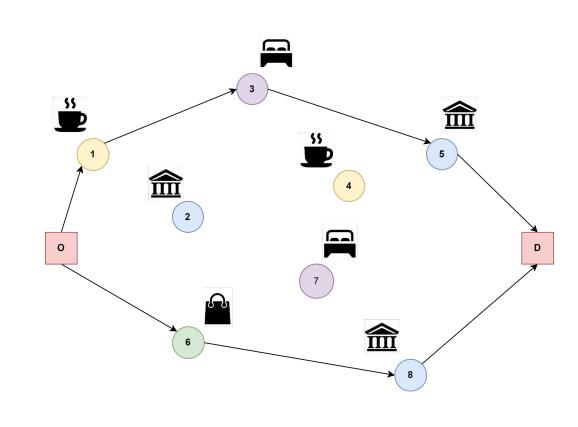
 Provide tourists with more diverse experience with TC constraints.



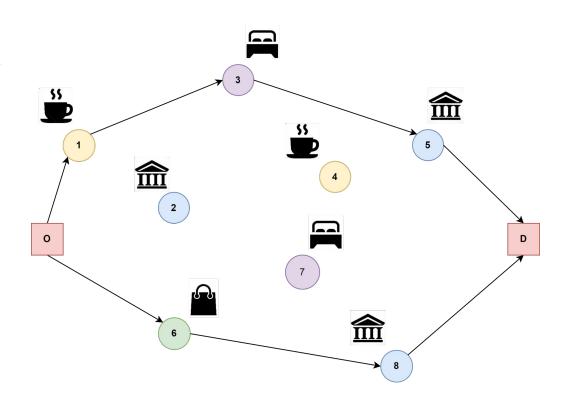
- Provide tourists with more diverse experience with TC constraints.
- Ensure each category or type of POI is visited throughout the trip.



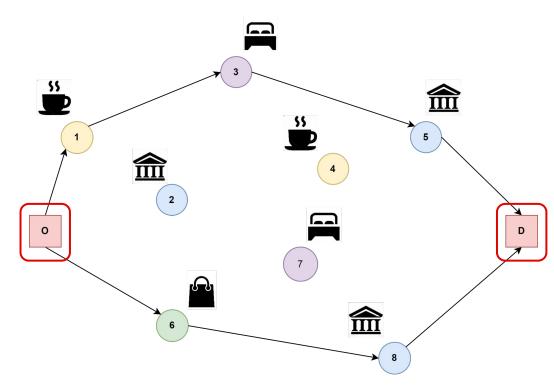
Part II: Problem Description



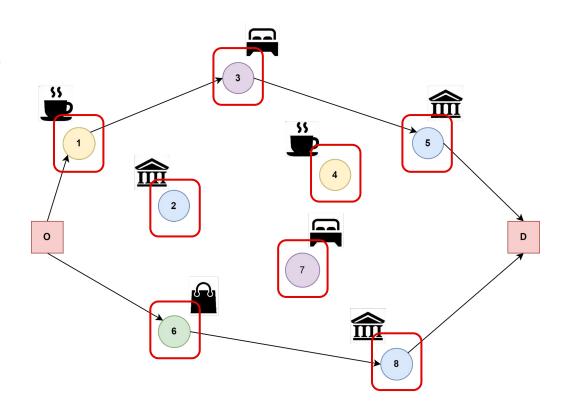
The TTDP-TC is represented as a directed graph.



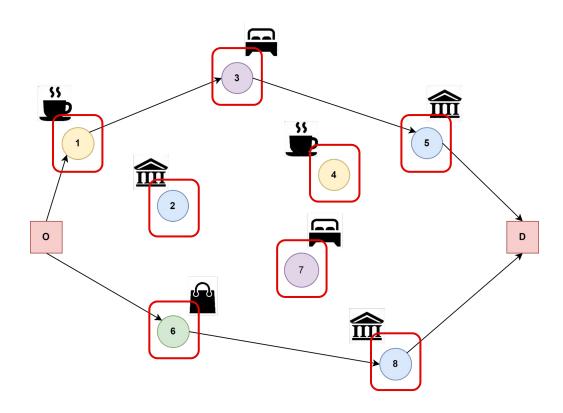
The TTDP-TC is represented as a directed graph.



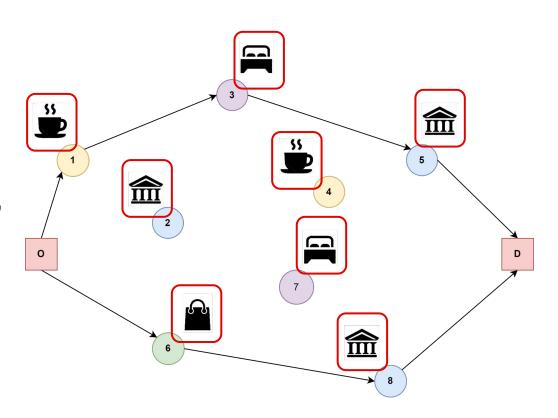
The TTDP-TC is represented as a directed graph.



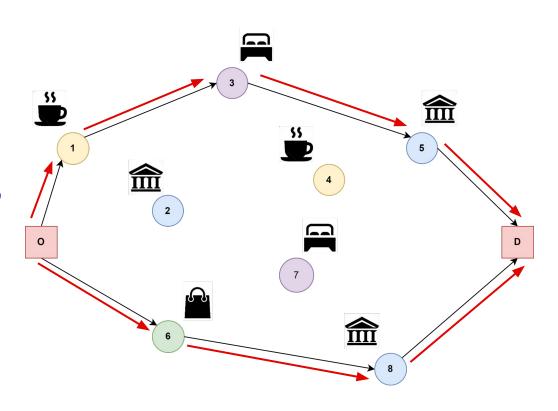
- The TTDP-TC is represented as a directed graph.
- Each POI has associated a profit value, indicating its preference.



- The TTDP-TC is represented as a directed graph.
- Each POI has associated a profit value, indicating its preference.
- POIs are grouped into categories, each POI belongs to one or more.



- The TTDP-TC is represented as a directed graph.
- Each POI has associated a profit value, indicating its preference.
- POIs are grouped into categories, each POI belongs to one or more.
- A travel time is defined for each directed arc.



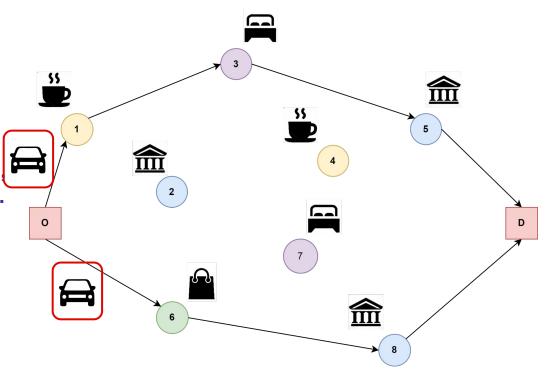
The TTDP-TC is represented as a directed graph.

 Each POI has associated a profit value, indicating its preference.

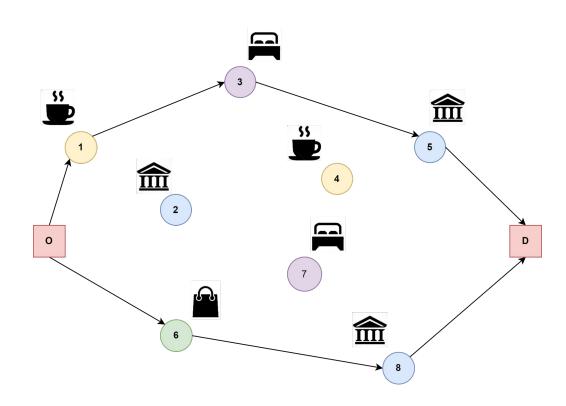
POIs are grouped into categories
 each POI belongs to one or more.

 A travel time is defined for each directed arc.

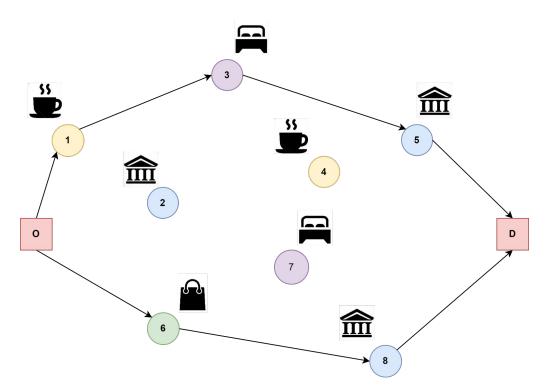
 Execute the m-days plan before maximum travel time.



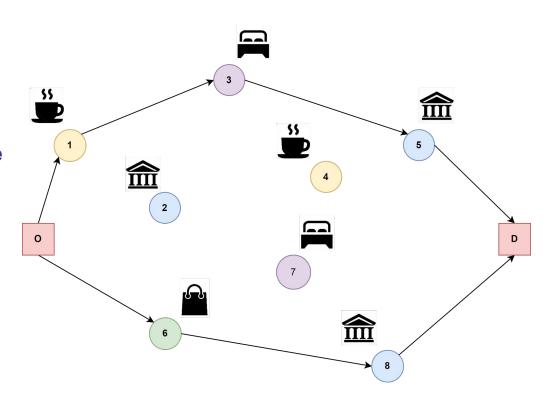
 To represent the problem, three variables are introduced.



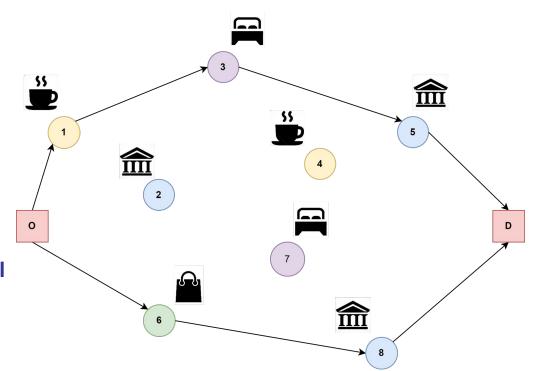
- To represent the problem, three variables are introduced.
- x_i□ variable to indicate if a vehicle travels from i to j or not.



- To represent the problem, three variables are introduced.
- x_i□ variable to indicate if a vehicle travels from i to j or not.
- y_i variable to indicate if POI i has been visited or not.

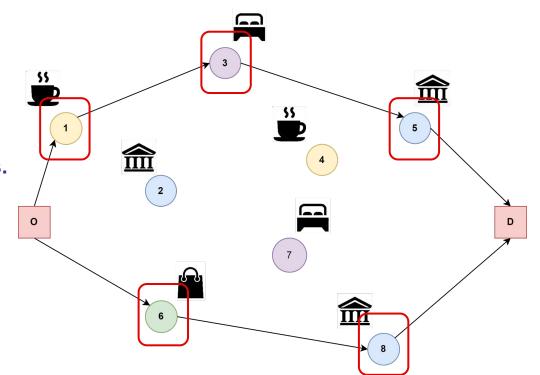


- To represent the problem, three variables are introduced.
- x_i□ variable to indicate if a vehicle travels from i to j or not.
- y_i variable to indicate if POI i has been visited or not.
- z_i variable to represent the arrival time to j coming from i.



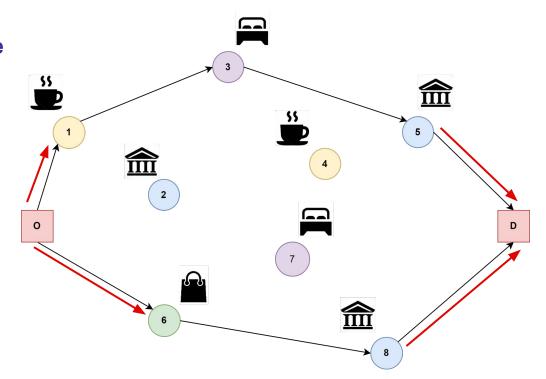
 Objective function is to maximize profit collected by the visited POIs.

$$\max \sum_{i \in N} p_i y_i$$



 Impose vehicle leaves m times the origin and finish at destination.

$$\sum_{j \in N} x_{0j} = \sum_{i \in N} x_{i,n+1} = m$$

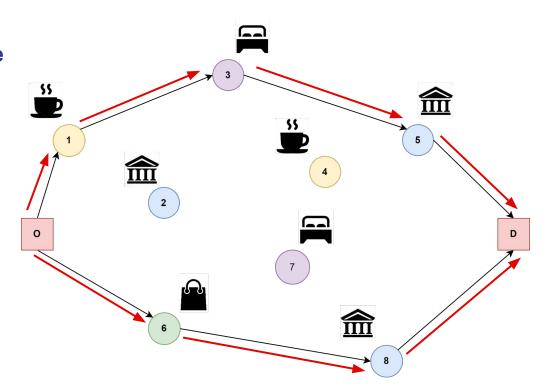


 Impose vehicle leaves m times the origin and finish at destination.

$$\sum_{j \in N} x_{0j} = \sum_{i \in N} x_{i,n+1} = m$$

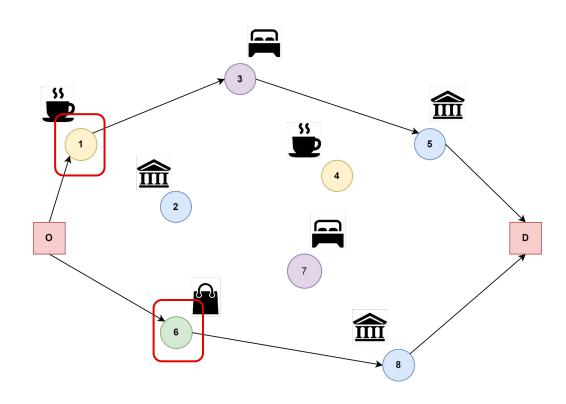
 Impose a POI is entered and left exactly once if visited.

$$\sum_{(j,i)\in\delta^{-}(i)} x_{ji} = \sum_{(i,j)\in\delta^{+}(i)} x_{ij} = y_{i}$$



Set arrival time starting from the origin depot.

$$z_{0j} = t_{0j} x_{0j}$$

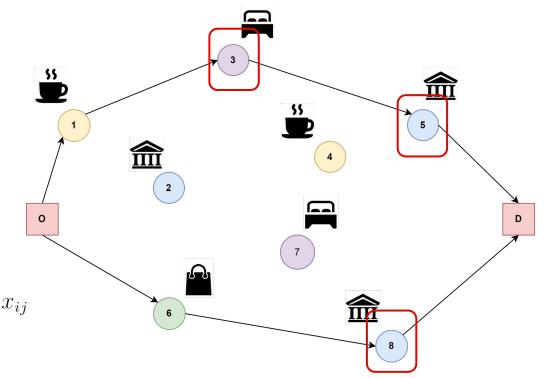


Set arrival time starting from the origin depot.

$$z_{0j} = t_{0j} x_{0j}$$

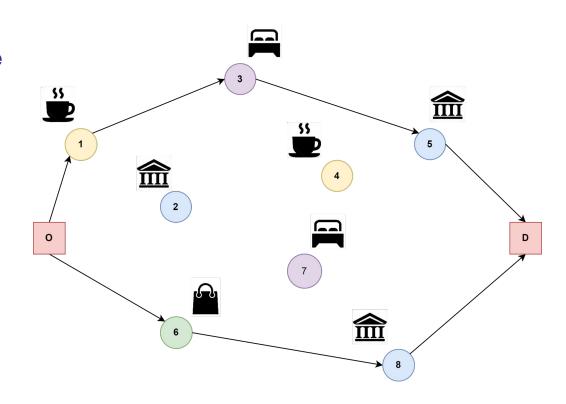
 Set arrival times coming out from each visited POI.

$$\sum_{(i,j)\in\delta^{+}(i)} z_{ij} - \sum_{(j,i)\in\delta^{-}(i)} z_{ji} = \sum_{(i,j)\in\delta^{+}(i)} t_{ij} x_{ij}$$



 Set the lower bound limits on the arrival time of each route.

$$z_{ij} \ge (t_{0i} + t_{ij})x_{ij}$$

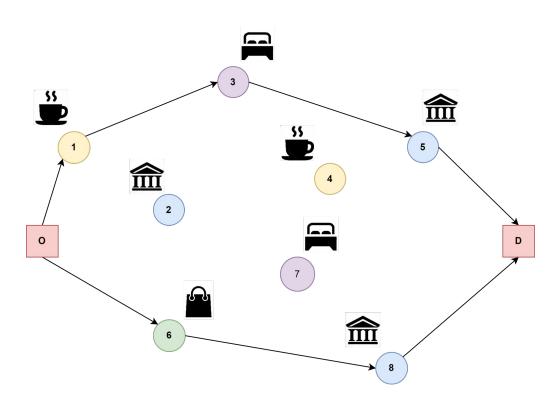


 Set the lower bound limits on the arrival time of each route.

$$z_{ij} \ge (t_{0i} + t_{ij})x_{ij}$$

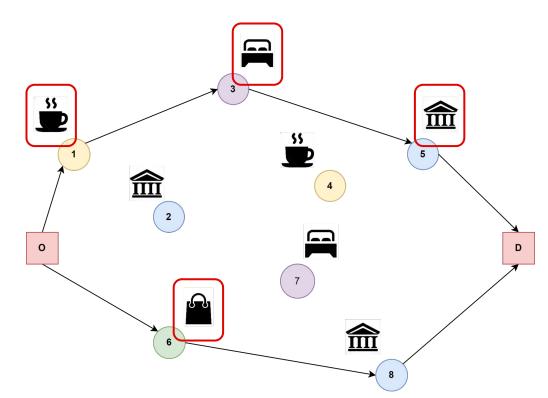
 Set the upper bound limits on the arrival time of each route.

$$z_{ij} \le (T_{\max} - t_{j,n+1})x_{ij}$$

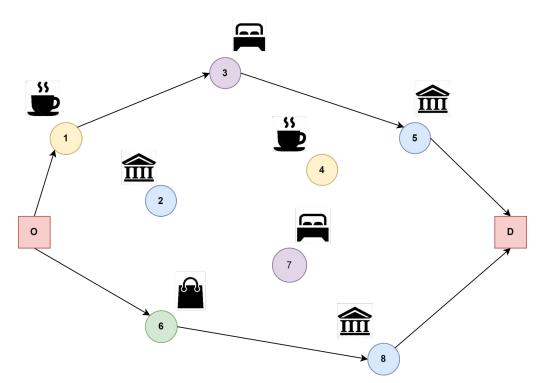


 Ensure for each category, at least one POI is visited.

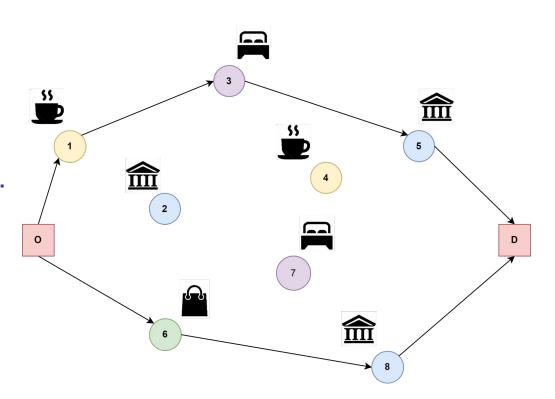
$$\sum_{i \in C_i} y_i \ge 1$$



 The formulation has polynomial number variables and constraints.



- The formulation has polynomial number variables and constraints.
- It can be used to solve instances of moderate size by optimizers.



Part III: Preliminary Results



 Extended instances proposed for the TOP, adding category types.

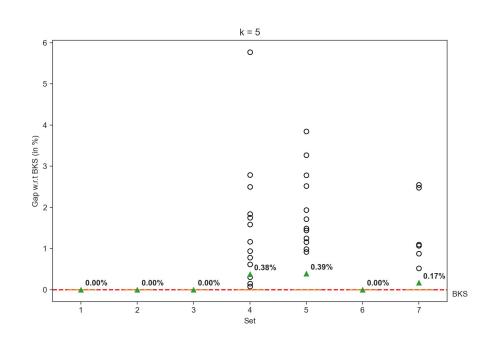


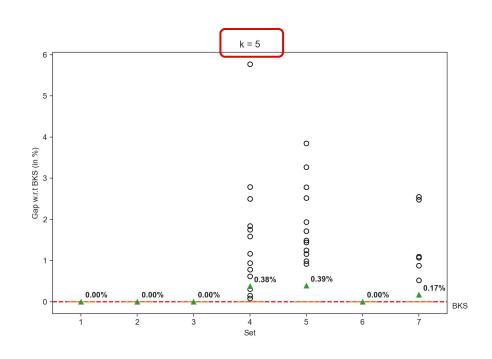
- Extended instances proposed for the TOP, adding category types.
- Commercial solver Gurobi used to test benchmark instances.



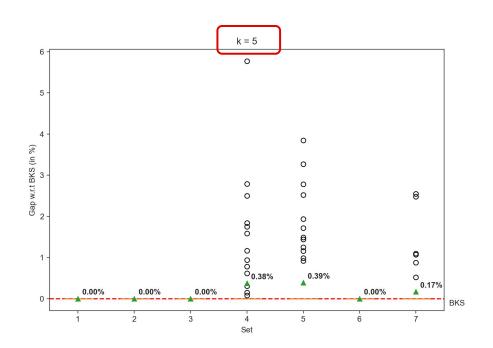
- Extended instances proposed for the TOP, adding category types.
- Commercial solver Gurobi used to test benchmark instances.
- A maximum time limit of 2 hours set to find optimal solutions.



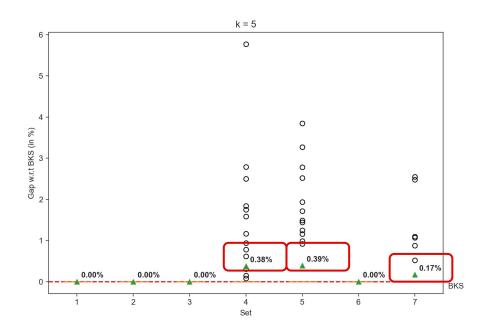


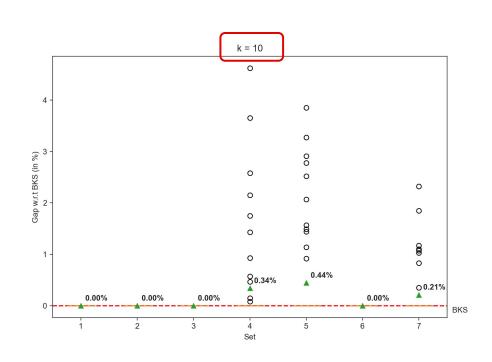


 Obtained optimal or near-optimal solutions for benchmark instances.

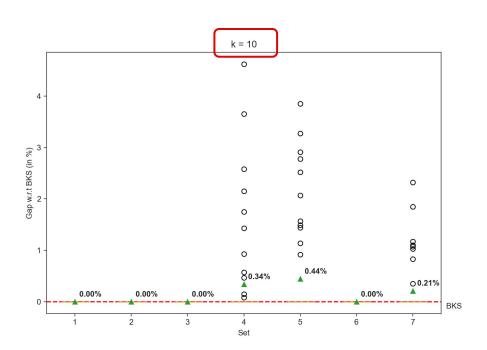


- Obtained optimal or near-optimal solutions for benchmark instances.
- Benchmark sets 4, 5, and 7 are the most challenging to solve.

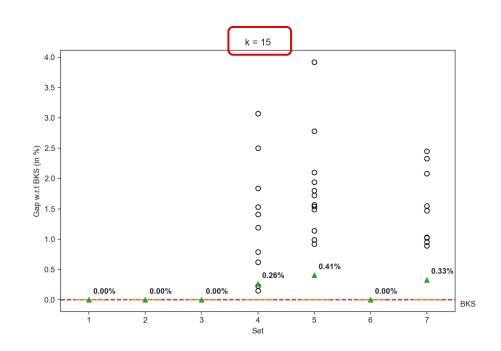




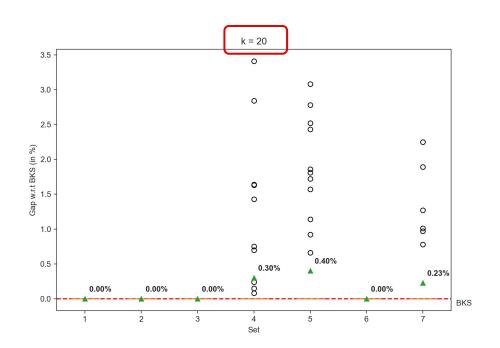
 As number of categories increases, instances become more challenging.



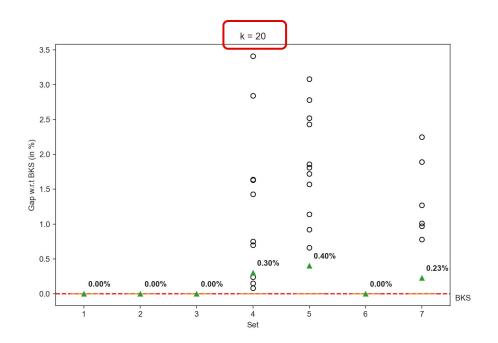
 As number of categories increases, instances become more challenging.



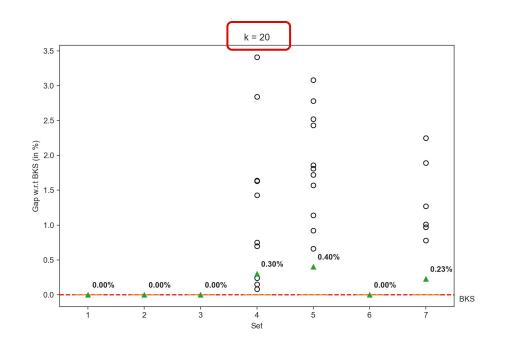
 As number of categories increases, instances become more challenging.



- As number of categories increases, instances become more challenging.
- Collected profit decreases as solutions become more diverse.



- As number of categories increases, instances become more challenging.
- Collected profit decreases as solutions become more diverse.
- Results are significant, with optimal solutions without complex methods.



Part IV: Conclusions and Future Research



 Proposed a novel and realistic version of the TTDP.



- Proposed a realistic and complex version of the TTDP.
- Considered TC constraints to provide more diverse routes.



- Proposed a realistic and complex version of the TTDP.
- Considered TC constraints to provide more diverse routes.
- Solved TTDP-TC with an exact method to provide optimal solutions.





Develop an agile optimization algorithm.



- Develop an agile optimization algorithm.
- Consider time-dependent POI availability.



- Develop an agile optimization algorithm.
- Consider time-dependent POI availability.
- Incorporate varying preference values for POIs based on experience.





Thank you for your attention!

Xabier Andoni Martín Solano

xamarsol@upv.es

Dept. of Applied Statistics and Operational Research, and Quality Universitat Politècnica de València, Campus de Alcoy, Spain





